

RULES GUIDE MAKEX CHALLENGE





Date	Version	Modifications Record		
2024.01	1.0	MakeX Challenge Ultimate Winner Rules Guide First Publish.		
2024.07	1.1	 4.2 Arena Optimized the illustration of starting area 4.3 Props Optimized the requirement of resource placement 5.1 Specification of Robot Construction Optimized the description of the robot construction 6.0 Competition Rules 6.2 Security Rules 6.3 Contestants' Requirements 6.4 Operation Rules 6.5 Modification Rules Updating the penalties for the competition, adding descriptions of penalties for specific behaviors, please refer to the rules above for details. 		





CONTENTS

1. Introduction
1.1 About MakeX1
1.2 MakeX Spirit1
1.3 About MakeX Challenge2
2.Competition Application
2.1 Participation Requirements 3
2.2 Registration and Application3
3. Competition Procedure 4
Onsite Registration4
4.Competition Details9
4.1 Introduction
4.2 Arena 10
4.3 Props
4.4 Missions24
4.5 Scoring Explanation
4.6 Single Match Flow
5.Technical Specifications
5.1 Specification for Robot Construction33
5.2 Specification for Team Flag39
6.Competition Rules 40
6.1 Penalty40
6.2 Security Rules
6.3 Contestant's Requirements43
6.4 Operation Rules44
6.5 Modification Rules48
7. Appeal and Arbitration

Ultimate Winner

7.1 Results Confirmation	49
7.2 Appeal Procedure and Valid Appeal Period	49
7.3 Invalid Appeal	50
7.4 Arbitration Procedure	51
8.Statement	52
8.1 Rules Explanation	52
8.2 Disclaimer	52
8.3 Copyright Declaration	53
Appendix 1. Awards and Annual Points	54
Appendix 2. Engineering Notebook Guideline	56
Appendix 3 Robot Self-Check Form	
Appendix 4 MakeX Challenge Score Sheet	62
Appendix 5 Instructions for Li-Po Battery	63
Appendix 6 Power Management Module	65
Appendix 7 Supplementary Explanation of Competition Procedure	70
Appendix 8 Competition Resources	72



1. Introduction

1.1 About MakeX

MakeX is an international robotics competition and education platform that promotes multidisciplinary learning within the fields of science and technology. It aims at building a world where STEAM education is highly appreciated and where young people are passionate about innovation by engaging them in exciting Robotics Competition, STEAM Carnival, Tech Event, Educational Conference etc.

As the core activity of MakeX, the namesake MakeX Robotics Competition provides exciting, challenging and high-level competitions in the spirit of creativity, teamwork, fun and sharing. It is committed to inspiring young people to learn Science (S), Technology (T), Engineering (E), Art (A) and Mathematics (M) and apply such knowledge in solving real-world problems.

1.2 MakeX Spirit

Creativity: we advocate curiousness and innovation, encouraging all contestants to create unique high-tech works with their talent, and challenge themselves for continuous progress!

Teamwork: we advocate solidarity and friendship, encouraging all contestants to develop a sense of responsibility and enterprising spirit, and sincerely working with their partners for win-win development!

Fun: we encourage contestants to build a positive, healthy mindset in the competition. Enjoy the journey and grow in the process.

Sharing: we encourage contestants to have an open mind as a maker and share their knowledge, responsibility, and joy with everyone, including their teammates and competitors.





MakeX spirit is the cultural cornerstone of the MakeX Robotics Competition. We hope to provide a platform for all contestants, mentors and industry experts to exchange ideas, study and grow up, and help young people acquire new skills during creation, learn to respect others in teamwork, gain an enjoyable life experience in the competition, take delight in sharing with the society their knowledge and responsibility, and work hard to achieve their grand aspiration of changing the world and creating the future !

1.3 About MakeX Challenge

MakeX Challenge is a highly confrontational competition program for students between the age of 11-18.

This program is very confrontational and enjoyable to watch, and the simple and easy-to-understand rules enhance the overall experience of participation and engagement. The design and construction of bigger robots and programming can better improve the contestants' design abilities and multi-dimensional thinking abilities of advanced robots. Also, the contestants are exercising logical thinking, strategic analysis, communication and cooperation, and improving decision-making abilities in the competition.



2.Competition Application

2.1 Participation Requirements

Participants: Contestants shall participate in a team. The number of contestants is 2-8 for each team, with 1-2 mentor(s).

Age: Team members must be teenagers or children between the age of 11-18 (born between January 2, 2005 and December 31, 2013). The mentor must be at least 18 years old.

Team Roles: Everyone in the team can play their respective roles as operator, observer, mechanist, programmer and so on. In each match, one team can only appoint 1 operator and 1 observer to participate, only two team members are allowed to compete in the competing area. The operator is responsible for operating the robot, and the observer is responsible for assisting the operator in observing the status of props and making suggestions.

Identification Symbols: Each team must have a team logo, team name, and team slogan. Teams are encouraged to use uniforms, flags, posters, badges, base decorations, etc. to show the team culture.

2.2 Registration and Application

Contestants and mentors that meet participation requirements can register on the designated competition webpage on MakeX official website (www.makex.cc/en). Each team should register with one registration form.

If participating team wants to change their members before competition, which leads to inconsistency with the registration information, they should inform MakeX Robotics Competition Committee in advance to finish re-registration.

For more details about the registration and application, please refer to <u>MakeX</u> <u>Registration & Competition Application Guide</u>

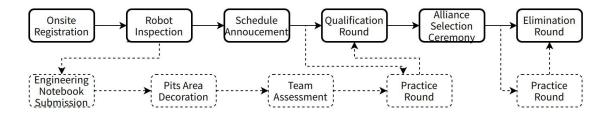
>>> 3 <<<< -</p>



3. Competition Procedure

Participating teams shall pay close attention to related notices and competition guide published before each competition. If there are some updates in competition guide, the latest rules will be adopted for the competition. MakeX Robotics Competition Committee reserves the rights and final interpretation to amend competition rules and system based on actual situation of different points race.

The schedule for each competition is determined by actual situation, and generally includes following procedures.



* Note: The solid line frame refers to the necessary procedure of each match, while the dotted line frame refers to non-essential procedure. Please keep abreast of updates.

Onsite Registration

When a team arrives at the venue, mentors and contestants should show ID cards or other valid certificates (e.g. passport) for onsite registration and to get the competition pack. Mentors must inform team members about the fire exit, match schedule, competition area, practice area and pits area, etc. Onsite registration and robot inspection will be conducted once the match schedule is generated.

Robot Inspection

Teams shall check their robots and team flag before the competition and complete the "**Appendix 3: Robot Self-Inspection Form**" according to the actual data. Teams that do not fill out the Robot Self-inspection Form in full according to the requirements cannot pass the inspection.

Before the competition, participating teams are obligated to conduct a self-check

and mutual check on their own robots and the opposing robots once again. They must promptly rectify any issues before entering the competing area.

Once get in the competing area, malicious complaints are not allowed (refer to 6.2, Operation Rule-R31 for the definition of malicious complaints). Participating teams must raise their hands in response to the referee's instructions to confirm that both robots are in proper condition before starting the match. Without a complaint, on-site inspections of robots are not permitted after this confirmation.

Schedule Announcement

The committee will announce the match schedule at least 30 minutes before the competition starts through online official website and onsite announcement. The schedule includes match-up chart, match session and specific time, red alliance and blue alliance, etc. If the two round of match are close together, please register at the Result Approval Desk.

Engineering Notebook Submission

Each team is required to submit 1 paper copy of their teams' engineering notebook to the MakeX staff at the inspection area. If you are unable to submit the original version, please prepare your own paper copy. The engineering notebook will be used as an important basis for the selection of the special awards, and the paper version of the engineering notes will not be returned after submission. For suggestions on how to write the engineering notes, please refer to "**Appendix 2: Engineering Notebook Guideline**".

Practice Round

Teams who have finished their robot inspection can participate in practice round. The schedule will be announced at the entrance in form of notices, and teams are required to queue in line before entrance. Not all competitions have a practice round, which can be informed based on actual situation.

Waiting for the competition

In regular competitions, a waiting area will be designated, and volunteers will announce or post information about the matches awaiting in that area. Participating teams are advised to pay attention to the waiting notifications and proceed to the corresponding waiting area according to the provided schedule.

Qualification Round

Normally, each team is requested to participate in four matches during qualification round. However, the session of qualification round may be different based on different competition. In qualification round, red alliance and blue alliance are matched randomly. Points will be obtained by teams according to the winning or losing situation. It is conducted in the form of alliances confrontation and each team's alliance and the opponents will be allocated randomly.

In each qualification round, team will receive corresponding points (including win, tie, loss) regardless of competition type. Three points for a win, one point for a tie, and no point for a loss. The final ranking is based on the sum of win-loss points, and the top-ranking teams will be promoted to the elimination round. If the team with the same win-loss points, the ranking sequence will be determined according to following rules:

1) The team with a higher total points differential of all qualification rounds has a higher ranking.

 If the above conditions are the same, the team with higher total scores among all qualification rounds has a higher ranking.

3) If the above conditions are the same, the team with the highest score of a single round in all qualifications round has a higher ranking.

4) If the above conditions are same, teams with the same ranking will play a one-on-one extra match, and those who with the highest total points will be the winner.

Alliance Selection Ceremony

In alliance selection ceremony, promoted teams will select their alliance team in turn according to their ranking in qualification round. Alliances that generated after the ceremony will be the alliances for the elimination round. The alliances will be named as "alliance 1", "alliance 2", "alliance 3"..... and so on according to the generated sequence. During this procedure, teams must abide by following rules:

When being chosen by other teams, promoted teams ranking top 50% can refuse for only once, and those teams ranking bottom 50% cannot refuse. If the team is refused by another team, they can continue to choose another team until the alliance is formed.

The promoted teams who are not present before the start of alliance selection are deemed as voluntarily giving up the right to choose alliance, and those who are not present before the end of the alliance selection are considered to be as voluntarily quitting the elimination round. If the promoted teams quit amid the alliance selection ceremony, the promotion places will be given to the following teams according to the ranking in the qualification round.

The promotion proportion for 2024 season competition is as follows. However, the promotion quota in different competitions may be different according to actual situation.

Number of participating teams	Number of promoted teams	
97 or more	64	
49-96	32	
25-48	16	
12-24	8	

Elimination Round

During the elimination round, the alliances generated in the alliance selection ceremony will be the opponent (red alliance and blue alliance are automatically matched) according to the competition schedule. The winner will be evaluated by BO3(Best of 3) and the alliance who achieve "two wins" or "one win and two ties" can advance to next round until the champion, runner-up and second runner-up are elected.

>>> 7 **<<**<

If the two alliances achieves "1 win, 1 loss, 1 tie" or "3 ties" in a BO3, the winning alliance will be decided according to the following rules:

>>>>>

1) If win-loss points are the same, alliance with higher total point differential in BO3 has a higher ranking.

2) If above conditions are the same, alliance with highest scores in BO3 has a higher ranking.

3) If above conditions are the same, alliances will play an extra match until the winner is elected.

Taking the promoted 32 teams as an example, the schedule of elimination round is as follows:



>>> 8 **<<<**



4.Competition Details

The theme of the 2024 MakeX Challenge is "Ultimate Winner".

4.1 Introduction

Each single match lasts for 4 minutes and 40 seconds.

MakeX Challenge Ultimate Winner is a confrontational competition, among which red and blue alliance for each match, and two teams for each alliance.

Each match comprises four stages: automatic stage, manual stage, modification stage and final stage. During the competition, contestants will control robots in automatic or manual mode to complete missions such as scrambling for combat supplies (cubes and cones) and placing them correctly, using flammable crystal silicon (the discs) to hit viral turret (the pins) and reversing flags or throwing them into the central smelter, etc.,. When the match ends, referees will calculate the points based on the final state of scoring props. The alliance with the higher point will be the winner.



Fig 4.1 Axonometric View of Competition Arena

4.2 Arena

The competition arena of MakeX Challenge Ultimate Winner consists of map and frame. It is a rectangular area with the size of 4640mm*3040mm and the frame's height is 400 mm. The arena mainly consists of starting area, own resource area, flag hanging area and the central resource area which is consisting of central smelter, reversed flag area and central resource island, etc.

The arena is evenly divides into the red and blue camps, with central resource area located in the central area. Robots are only required to conduct corresponding missions in their respective camp except for the final stage. During the final stage, the robots are allowed to go into the opponents area as permitted by the rules.

Starting Area

The starting area is where robots are placed before the competition, they are located at the four corners of the arena. There are two starting areas for each red alliance and blue alliance., with the size of 500mm × 500mm

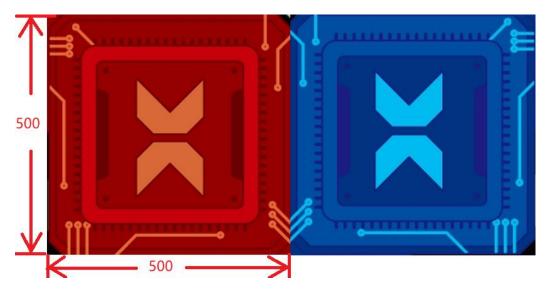


Fig 4.2-2Starting Area

Own Resource Area

There is one own resource area each camp, which is divided in two layers. The upper layer is called the resource drop area, which is consisting of 3 areas with dimensions of 333mm*200mm, the 3 areas is placing with a alphabet cube, 5 discs and a cone



from left to right. Before the match, these three sets of resources were all placed outside the arena. Before the final stage, the alliance that has acquired the rights need select one additional set resource and then partially or completely place that resource into the starting area of the arena.

The lower layer is called the pin placement area which is consisting of 3 areas with dimensions of 200mm(width)*986mm(length), of each area placing with 4 pins. In each area, the distance between each pin is same. There are 12 pins in each camp.

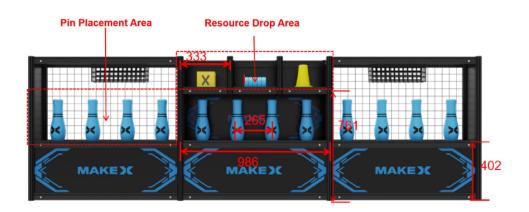


Fig 4.2-3 Own Resource Area(Front View)

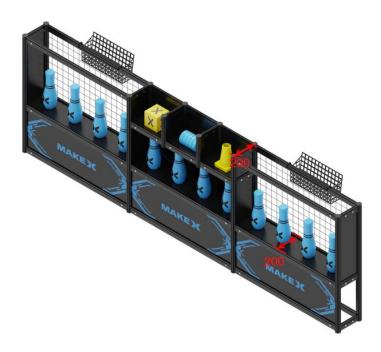


Fig 4.2-4 Own Resource Area(Axial View)



Central Resource Area

There is one central resource area located between the two camps with the dimension of 3040mm*1044mm. The central resource area is divided into the central part and the left and right part. Each left and right part is divided into 2 layers, the upper layer is called the reversed flag area with the dimension of 1000mm*200mm. The lower layer is called the movable resource island with the dimension of 1000mm*200mm. The central part is consisting of the central smelter and the central resource island.

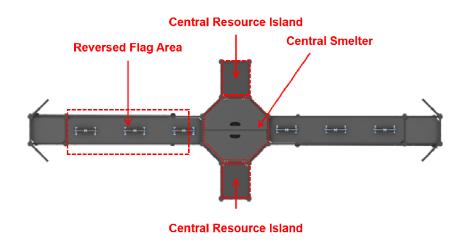
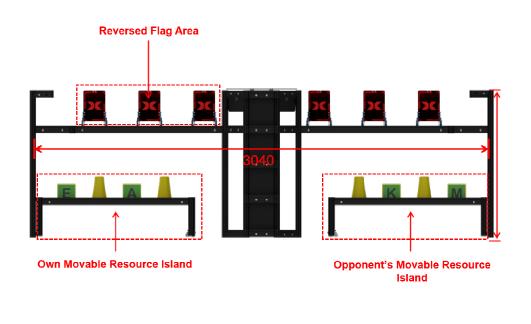


Fig 4.2-5 Central Resource Area(Top View)



>>> 12 <<<<





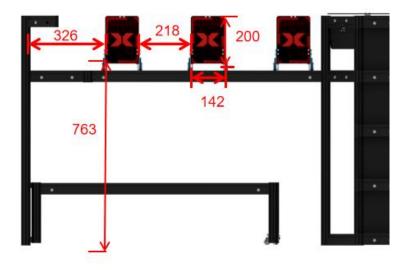
Fig 4.2-6 Central Resource Area(Front View)



Fig 4.2-7 Central Resource Area(Axial View)

Reversed Flag Area

The reversed flag area is located in the upper layer of the left and right part of the central resource area. Each side of the reversed flag area have fixed with 3 reversal flags, of total 6 reversal flags at the reverse flag area. The size of the reversal flag is 142mm*200mm. The distance between the bottom of the reverse flag and the ground is 763mm, and two adjacent reverse flags on the same side are 218mm apart.



>>> 13 <<<



Ultimate Winner

Movable Resource Island

The movable resource island is located in the lower layer of the left and right part of the central resource area. At each side of the movable resource island, there are 2 alphabet cubes and 2 cones respectively placed in the groove with the dimension of each groove is 120mm*120mm*20mm (length*width*height). The position of the cubes and cones are fixed as shown and cubes are placed in a randomized order. The height from the ground to the top of the resource island is 252mm. The portion size of the alphabet cube protruding from the resource island is 90mm, and the portion size of the cone protruding from the resource island is 140mm. The bottom of the movable resource island is equipped with movable rubber wheels, which can be rotated unidirectional around the axle. The movable resource island facing the left side of the central resource area is the movable resource island that can be pushed out by the own alliance, with the left and right sides being symmetrically arranged in the center.

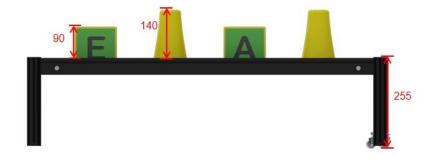


Fig 4.2-9 Movable Resource Area(Front View)

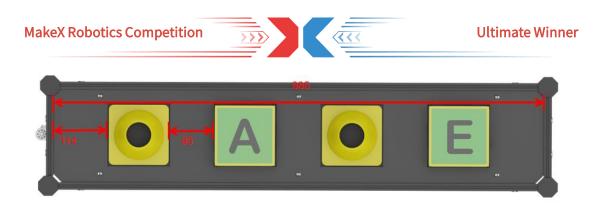


Fig 4.2-10 Movable Resource Area(Top View)



Fig 4.2-11 Groove(Top View)

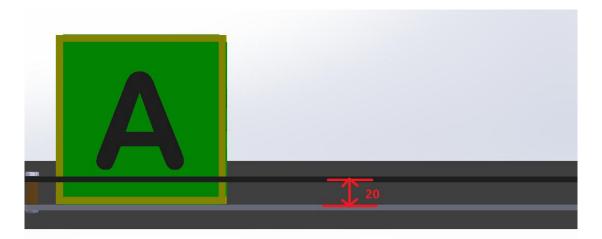


Fig 4.2-12 Groove(Front View)

Central Smelter

The central smelter is located in the centre of the two camps and it is an octagonal shape that consisting by flat beam with the length 160mm and octagonal pillar, with an internal diameter of 465mm and an overall height of 960mm. There are four smelting ports with dimensions of 179mm*160mm on the sides of the central

- >>> 15 <<<<-



smelter, located on the four inclined sides, with a height from the ground to the bottom of the port of the port of the smelter of 735mm, and the upper part of each port is equipped with a reversible baffle with dimensions of 90mm*160mm.

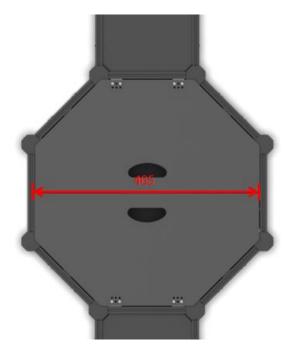
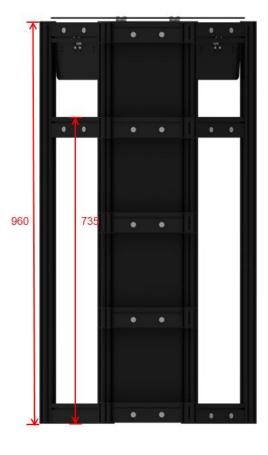


Fig 4.2-13 Central Smelter(Top View)



->>> 16 <<<





Fig 4.2-14 Central Smelter(Front View)

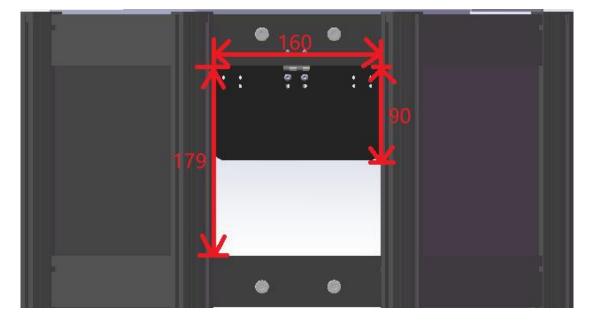
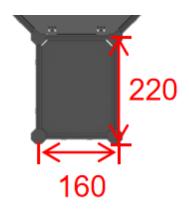


Fig 4.2-15 Smelter Ports (Top View)

Central Resource Island

The central resource island is located in the central position of the two camps, the red and blue camps each have one central resource island. The central resource island is composed of five rectangular resource trays that made with 160mm and 220 flat beam and octagonal pillar, combined in regular rows perpendicular to the ground, the overall height of 965mm, the lowest resource tray is 49mm from the ground, and the distance between the two neighboring resource tray is 228mm.



17

<<<



Fig 4.2-16 Resource Tray (Top View)

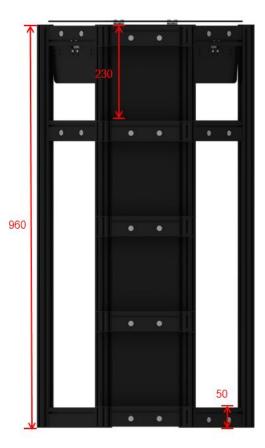


Fig 4.2-17 Central Resource Island (Front View)



Fig 4.2-18 Central Resource Island (Side View)

->>> 18 <<<-



Flag Hanging Area

Each side of the camps has 2 symmetrical flag hanging devices, a total of 4 in the whole arena, the height of the flagpole from the ground is 960mm, the length of its transverse flat beam is 160mm, the flat beam is oriented towards the field and the side frame is at 45 degrees, which is used to hang the team flag.

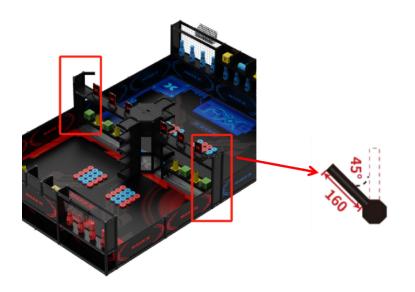


Fig 4.2-19 Flag Hanging Area (Side View)

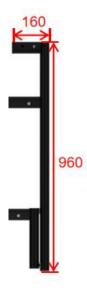


Fig 4.2-20 Flag Hanging Area (Front View)

19





Discs Placement Area

Each side of the camps has 2 discs placement area area with the dimension of 400mm*400mm. Each area has placed 16 pieces of discs. The discs placement in the red camps is as shown in fig-1 and the discs placement in the blue camps is as shown in fig-2. Both alliances can collect discs on the arena to hit opponents' pin, reverse flag or shoot into the central smelter.

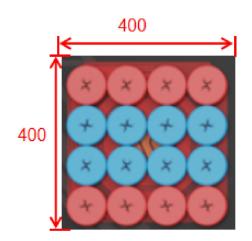


Fig 4.2-21 Red Alliance Discs Placement Area (Top View)

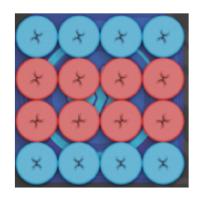


Fig 4.2-21 Blue Alliance Discs Placement Area (Top View)

4.3 Props

The initial position of the props before the match is shown in figure:

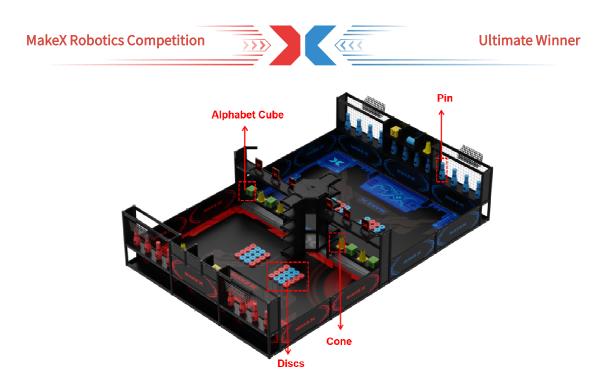


Fig 4.3-1 Arena Prop Placement

Flammable Crystal Silicon(Discs)

Flammable Crystal Silicon(i.e. discs) is the red/blue discs that placing at the discs placement area in each camp and their own resource area. The material of discs is EVA and the dimension is 30mm(height) and diameter 100mm. Before the start of match, each discs placement area will placing with 16 pieces of discs and a total of 64 discs in the arena. Robots can complete the mission by shoot the discs to hit the opponents' pin and the reserve flags or directly shoot the discs into the central smelter.

21



Fig 4.3-2 Blue Discs



Fig 4.3-3 Red Discs



Viral Turret(Pins)

Viral turret(i.e. pins) is the red/blue pins that placing at the own resource area at each camp. The material of discs is EVA. The height of each pin of 290mm, diameter of the bottom of each pin is 70mm, and the maximum diameter is 100mm. Each camp has 12 pins and a total of 24 pins in the arena. Contestants can control the robot to shoot the disc to knockdown the opponents' pin.



Fig 4.3-4 Blue Pin



Fig 4.3-5 Red Pin

Human Datacube (Alphabet Cube)

Human datacube(i.e. alphabet cube) is the cube that placed in the movable resource island at the center resource area in the arena. It is made of EVA with an edge length of 120 mm with the bottom side having a hollow cross hole(as shown). There are 4 cubes in total. The alphabet cube labeled with "M," "A," "K," and "E" each have one, and the cube labeled with "X" is not set in the arena. It can only be obtained by completing missions. This prop is a common prop for both participating alliances. The alphabet cubes are allowed to be used to accomplish the Scrambling resources mission. (Note: A tolerance of ±5mm is permitted for all props)

>>> 22 **<<**<

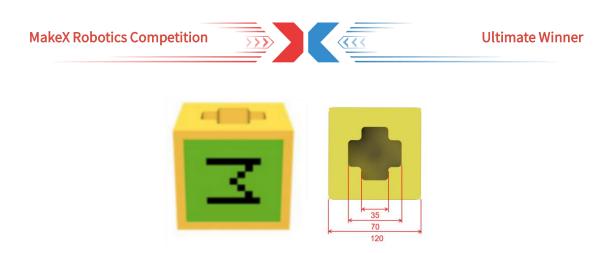


Fig 4.3-6 Alphabet Cube

Missile Launcher(Cone)

Missile Launcher (i.e. Cone) is placed on the movable resource island in the resource area in the central resource area of the arena. Material: EVA. Dimension: the overall height is 170mm, the pedestal is a square with a side length of 120mm*120mm, a height of 20mm and a rounded corner with a rounded hollow in the center of 80mm in diameter; the upper part is a rounded corner with a diameter of 100mm at the lower bottom and 60mm at the upper bottom with a rounded hollow in the center of 50mm in diameter. There are 4 cones in total, multiple cones can be obtained by completing mission, this prop is a common prop for both alliances. The cones are allowed to be used for completing the Scrambling resources missions.



Fig 4.3-7 Cone(Front View)

>>> 23 <<<.

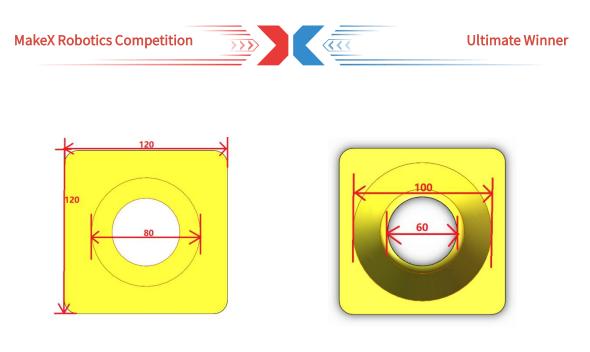


Fig 4.3-8 Cone(Elevation view)



* Note: All arenas and props have certain and reasonable tolerances. If there are any objection to the size of the props or other problems, the captain of alliance can apply for replacement before the match, and the final decision is on referee.

4.4 Missions

The competition unfolds through various stages, including automatic stage, manual stage, modification stage and final stage. Mission details of each stage are detailed below:

Stage	Mission Details	Operation Area
Automatic Stage	(1) Scrambling for resources	Individual Camp
(30 seconds)	(2) Knocking out the pins	
	(3) Shooting the discs into the smelter	
	(4) Hitting the reversal flag	
Manual Stage	(1) Scrambling for resources	Individual Camp
(100 seconds)	(2) Knocking out the pins	

24

~<<



	(3) Shooting the discs into the smelter	
	(4) Hitting the reversal flag	
Modification Stage	Modification of individual robots	Off-site
(60 seconds)		
Final Stage	(1) Scrambling for resources	Whole arena
(90 seconds)	(2) Knocking out the pins	
	(3) Shooting the discs into the smelter	
	(4) Hitting the reversal flag	
	(5) Hanging the team flag	

Scrambling for Resources

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Missions Details: Robots are tasked with securing alphabet cubes or cones from the movable resource island located in the central resource area. The objective is to accurately position these alphabet cubes or cones into the five resource trays on their respective central resource island.

Scoring State Judgement: It's regarded as a valid state if the vertical projection of the alphabet cube or cone is entirely within the resource trays of their corresponding central resource island, and there is no interaction between the props and the robot.

Mission Points: Each correctly placed alphabet cube or cone is awarded 30 points. An additional bonus of 100 points is granted if all five resource trays on a central resource island are filled with valid alphabet cubes or cones.

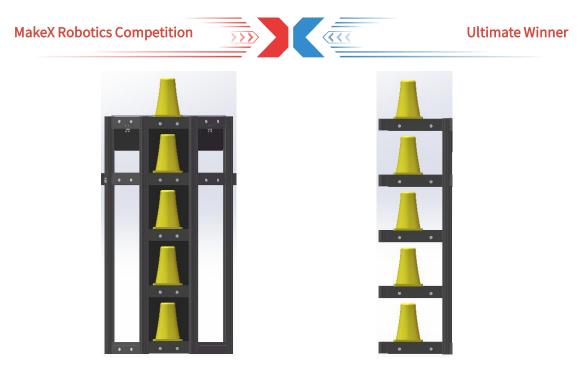


Fig 4.4-1 Cone Placement(Front view)



Knocking out the pins

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Missions Details: Robots from both teams are equipped to gather discs and launch them within their own camps to topple the opposing team's pins, thereby decreasing their score. Alternatively, they may act defensively to protect the initial position of their own pins from being altered by the opponent.

Scoring State Judgement:

a. The team's own pin must be upright, with its base fully in contact with the pin placement area in the lower section of their resource area.

b. The team's own pin must not be in direct contact with their robot.

Mission Points: All the above conditions are considered as valid scoring states. 10 points for each pin.

Shooting the discs into the smelter

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Missions Details: Robots are permitted to collect discs of their own color and aim to

>>> 26 <<< -



shoot them into the central smelter.

Scoring State Judgement: A disc is considered correctly placed if its vertical projection is wholly inside the central smelter.

Mission Points: All the above conditions are considered as valid scoring states. 20 points for each disc.

Hitting the Reversal Flag

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Missions Details: Robots are equipped to gather discs and launch them at the reversal flag situated in the Reversal Flag area above the Central Resource area. The objective is to cause the reversal flag to tilt toward the opponent's side.

Scoring State Judgement: it is considered a valid state if the reversal flag is tipped at any angle toward the opponent.

Mission Points: Each valid state flag counts 20 points.

Benefit Acquisition: At the conclusion of the manual stage, if an alliance manages to tilt all three reverse flags on one side of the reverse flag area toward the opponent, any robot from that alliance is permitted to relocate their own movable resource island. Furthermore, both robots from the alliance may enter the opponent's camp. Concurrently, the alliance may select one benefit from the options below. If an alliance successfully tilts all reverse flags in the reverse flag area (both left and right sides) toward the opponent, they may choose two benefits. The benefit options are:

- a. Gain 1 alphabet cube marked "X".
- b. Gain 1 cone
- c. Gain 5 discs

Upon receiving the benefits, alliances must place the acquired resources (props) partially or completely into any starting area of one's own camp before the final stage. If an alliance receives two benefits, they cannot be identical.



Hanging the Team Flag

Operation Stage: Final Stage.

Missions Details: Robots are authorized to suspend the team flag on the flagpole located either in their own or the opponent's flag-hanging area. Each team may introduce one flag into the arena per match.

Scoring State Judgement: A flag hanging is deemed valid if, during the scoring moment, the flag is affixed to the flagpole without any contact with the ground or the robot. The flag must be in a naturally unfurled state and adhere to the prescribed manufacturing standards. A flag that remains folded due to contact with other elements is classified as an invalid hanging.

Mission Points: A valid flag hanging in the own camp earns 30 points. Conversely, a valid flag hanging in the opponent's camp secures 50 points. There is no limit to the number of valid flags in either camp's hanging area.

MakeX Bonus

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Missions Details: Robots are tasked with collecting five alphabet cubes and arranging them in a vertical sequence from top to bottom as $\lceil M \rfloor \lceil A \rfloor \lceil K \rfloor \lceil E \rfloor \lceil X \rfloor$ in the resource trays of their respective central resource island.

Scoring Statement Judgement: A scoring state is acknowledged if five alphabet cubes are orderly positioned from top to bottom as $\lceil M \rfloor \lceil A \rfloor \lceil K \rfloor \lceil E \rfloor \lceil X \rfloor$ in the resource trays of the respective central resource island. The vertical projection of each alphabet cube must entirely occupy the corresponding resource area without any contact with the robot.

Mission Points: A successful MakeX Bonus sequence is awarded an additional 150 points.

>>> 28 **<<**

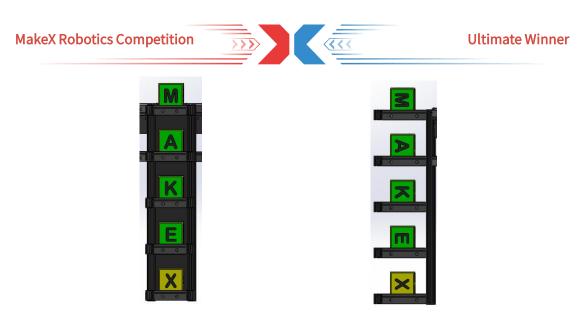
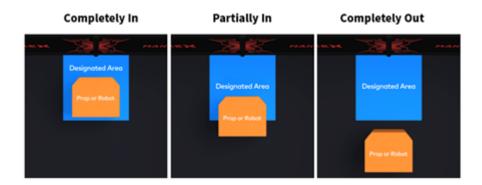


Fig 4.4-3 Cube Placement(Front view)

Fig 4.4-4 Cube Placement(Side view)

Boundary State Judgement

During the match, if there is any uncertainty about the position of the robot (or props) and designated boundary, the following state judgement can be explained:



4.5 Scoring Explanation

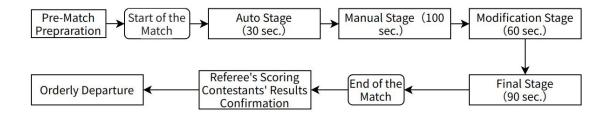
The final score of the match is determined by the final static state of the scoring prop after the match. Competition missions, scoring props and its corresponding points are as follows. After the competition, the referee calculates the sum of scores of each mission, and the alliance with the higher score will be the winner.

Scorin	g Props	Details of Scoring Props	Single Prop's point	Maximum Quantity	Maximum Point
D	isc	Discs of own color in the	20	37	740



	central smelter			
Pin	Valid state pins at the respective camp	10	12	120
Reverse Flag	Reverse flag tipped to opponent's camp	20	6	120
Alphabet Cube	Alphabet cube placed in the central resource island in a valid state	30	5	150
	Five alphabet cubes all placed in the central resource island in a valid state	100	1	100
	Alphabet cubes placed in the central resource island in the order of "MAKEX" from top to bottom	50	1	50
Cone	Cone placed at the central resource island in a valid state	30	5	150
	Five cones all placed in the central resource island in a valid state	100	1	100
Team Flag	Valid Flag in Own Flag Hanging Area	30	2	60
	Valid Flag in Opponent's Flag Hanging Area	50	2	100

4.6 Single Match Flow



Pre-Match Preparation

Before a single match, contestants are required to check if their robots comply to the

->>> 30 <<<<-

rules requirement and the power management module has installed correctly and work properly in the inspection area.

After entering the field, the both alliances should check whether the arena and props are placed in a standard way, and whether the robots of both alliances are in a standard way. After cross-checking and approval, please follow the referee's instruction and wait for the competition to start.

Start of the Match

Contestants are not allowed to contact the robot after referee's instruction to start the competition.

Automatic Stage

The automatic stage lasts for 30 seconds.

To ensure the competition fairness, robots in the starting area are required to power off. After the countdown of automatic stage, operator should turn on the robot and the robot can run the preset automatic program.

Manual Stage

The manual stage lasts for 100 seconds.

After the automatic stage ends, there is a preparation period before the manual stage begins. After the 5 seconds countdown by the referee, the 100 seconds manual stage begins. In manual stage, the operator can control the robot with Bluetooth controller.

Before the end of the manual stage, the referee will give a 5 seconds countdown reminder. After countdown, the competition will move on to the modification stage. **Modification Stage**

The modification stage lasts for 60 seconds.

The modification stage begins after the end of manual stage. Contestants are allowed to remove their robots (the vertical projections of the robots must partially or completely in the starting area.) out of arena and modify them. There are specifications for the length and width of the modified robot, and the height is not limited. (Please refer to 6.3 Modification Rules for the specifications.)

During the final 30 seconds of the enhancement modification stage, the competition system will issue a notification. As the enhancement modification stage approaches its end, there will be a 10-second countdown. Before the countdown concludes, contestants must return their robots to the starting area (partially or completely). If, after the countdown ends, a participating team has not returned their robot to the starting area (partially or completely), the team's robot will be disabled during the modification stage. Once the robot is partially or completely placed in the starting area, if there are any acquired resources, competitors must request approval from the referee and partially or completely place the selected resources into their own starting area.

Final Stage

The final stage lasts for 90 seconds.

Before the final stage begin, the referee will determine whether or not both sides have been acquired the benefit(s) based on the status of the reverse flag on the arena. If one side is acquired the benefit(s), the alliance captain shall immediately makes the relevant entitlement selection and implements it.

After a five-second countdown, final stage begin and the operator can control the robot with Bluetooth controller. During this stage, the alliance that acquired the benefit is allowed to operate their robots in the opponent's camp. At the end of the final stage, the competition will have a five-second countdown by referees. After the end of the match, the operator is required to stop controlling the robot and place the Bluetooth controller in the storage basket and stay out of the arena.



5.Technical Specifications

5.1 Specification for Robot Construction

The specification for robot construction provides a fair and safe competition standard for all teams and the committee encourages teams to make innovative designs of their robots on the prerequisites of meeting these specifications. The committee encourages teams to conduct hardware construction and software programming on the premise of observing the specifications. During the competition, it is a must for robots to abide by the specifications. Any robot that violates the specifications will be required to be modified. Those who commit serious offense will be punished for canceling the results or disqualification.

Robot Mechanical Specification

T01. The size specification of the robot is: before the modification stage: 500mm (length)*500mm (width)*700mm (height) ; After modification: 500mm (length) x 500mm (width), and with unlimited height. The length and width of robot are defined before the competition, without redefinition after the competition. When measuring the robot size, the flexible material on it should not be affected by external forces. (The flexible material includes but not limited to rolled strip, tape, foam block, etc.).

	Requirements	Details
Maximum	500 mm (Length)	1.The height should not exceed 700 mm and the vertical
Initial Size	500 mm (Width)	projection of the robot should not exceed the square
	700 mm (Height)	area of 500 x 500 mm.
		2.Before the modification stage, the robot's size must
		comply with the requirement of maximum initial size.

33 <<<

Modified Size 500 mm (Width) pro Unlimited (Height) the 2. A con size 3. T	There is no limitation on height and the vertical ojection of the robot on the arena should not exceed e rectangular area of 500 x 500 mm. After the modification stage, the robot's size must omply with the requirement of the maximum modified ze. The team should show the maximum size of the robot uring the inspection.

T02. The maximum net weight of the robot (during any time of the competition) shall not exceed 10 kg, including the weight of battery, all parts of the robot and excluding team flag.

T03. The robot must have a symbol with the team number or team name, with a single character higher than 3.5cm and a light background color so that the team can be clearly identified during the competition; if the symbol does not meet the requirements, the robot won't able to pass the inspection.

T04. Driving system: The main-board and moving robot chassis, including wheels, tracks or other mechanism structure that bring the robot into direct contact with the ground and move it over a flat field surface. For stationary robots or robots without a moving mechanism, the structure in direct contact with the ground is considered the driving system.

T05. One team is only allowed to participate in competition with one robot. Teams may modify other structures of their robots during the Modification stage but cannot modify the driving system. If a team modifies the driving system, the team is considered to be using another robot and will be penalize by disqualification.

T06. If replacement of some component because of its broken (e.g., wheel damage, motor failure, main-board failure, etc.), it is not considered as the replacement of the

->>> 34 <<<---



driving system.

T07. The parts can be lubricated with lubricant, but contestants should protect the arena from lubricant leaking.

T08. The following robot's parts that may cause danger are forbidden:

- (1) Sharp angle;
- (2) Oil pressure parts or hydraulic parts;
- (3) Switches or contacts containing mercury;
- (4) Parts that will conduct electrical current from robots to arena;
- (5) Parts that tend to develop connections with other robots, such as hook-shaped parts and other parts;
- (6) Other dangerous parts as determined by the referees.

T09. The following hazardous materials are forbidden:

- (1) Flammable and explosive gases;
- (2) Materials containing liquids or gelatinous substances (except for glues and lubricants used in prescribed and small quantities);
- (3) Materials that may cause arena contamination, such as sand, ink, etc.;
- (4) Materials made from animal tissue;
- (5) Materials that may cause danger as determined by referees.

T10. The equipment with high performance that infringes the competition fairness is prohibited, which must be operated with following performance indicators:

Equipment	Component	Specification	Note
Motor&	DC Motor	• 25 DC Motor	Total amount of DC motor
Servo		Rated Voltage: 6V	and encoder monter ≤13
		Rated Rotation Speed: 50&200RPM	Total amount of servo≤6
		• 37 DC Motor	Total amount of





Ultimate Winner

		Rated Voltage: 12V	brush-less motor≤2
		Rated Rotation Speed: 50&200RPM	
	Brush-less	2823/2824 Brush-less Motor	It is forbidden to change
	Motor	Rated Voltage: 10000 mA MAX	the mechanical structure
		Rated Rotation Speed: 7300 rpm	and electrical layout of
	Encoder Motor		any motor or servo. Allows external welding
			without changing the
			performance of the
			motor.
		MS-12A Smart Servo	
		Working Voltage: DC6V~12.6V	
		Torque: 12kgf.cm	

Robot Electronic Specification

T11. Except for laser sighting device, each robot can only be equipped with one battery, and the battery must be fixed inside the robot. The battery is prohibited from colliding with and separating from the robot.

T12. If the team use laser sighting device on their robot, the power of the laser sighting device should be less than or equal to 5mW (below Grade 3 a/R), and at most one laser sight for one robot.

T13. The battery cables shall be intact without cracks, breakages and metal wires. There must be an electrical isolation between power supply lines and robot structures.

T14. The electronic equipment with high-performance that infringes competition fairness is prohibited, which must be operated with following performance indicators:

>>> 36 <<< -



Ultimate Winner

System	Module	Specification	Note
Power System	Li-Po Battery	• 3S Li-Po Battery	
		Output Voltage: 11.1V	
		Discharge Rate: 25-30c	
		Battery capacity: 4200mAh	
Main-board	Main-board	• Processor: High Performance M7	Allowed to use
System		Processor	Raspberry Pi 3 Model
		ATSAMS70N20A-ANSTM32F030CC	B+ at the same time
		T6 Co-processor	
		Working Voltage: 6V ~ 13V(The	
		minimum input voltage of motor is	
		required to meet the requirement of	
		motor's working voltage)	
		Communication Ports and Protocols:	
		Serial Port /mBuild Protocol	
Sensor System	Vision Sensor	Viewing Angle: 65.0 degrees	Type and quantity are
		Effective Focal Length: 4.65±5%mm	not limited.
		Identification Speed: 60 frames/seconds	It is forbidden for
			robots to use any
		best range	sensors that will
		Method of Power Supply: 3.7V Lithium	interfere with the
		Battery or 5V mBuild Power Module	perception ability of
			other robots
		Power Consumption Range: 0.9-1.3W	
Wireless	Bluetooth	Bluetooth Version: Support 4.0+	 During the
Control System	Controller	Distance of Remission: 20m	competition, one
		Working Current: ≤25mA	Bluetooth



Ultimate Winner

	Transmit Power: 4dBm	controller is
	Transmit Data: Data packets within	available for one
	100ms can be acquired by Bluetooth	team;
	devices (low latency)	• The Bluetooth
	Battery: Two No.5 AA Dry Batteries	module shall
	Supported Platform: macOS / Windows	connect with Nova
	Supported Hationn. macos / windows	Pi mainboard
Bluetooth	Bluetooth Version: BT4.0	It is forbidden to use
Module	Band Range: 2402~2480MHz	any form of wireless
	Antenna Gain: 1.5dBi	control device to
	Energy Consumption Grade: ≤4dBm	communicate with
		robots other than the
	Working Current: 15mA	official Bluetooth
		controller, including bu
		not limited to any
		artificially triggered
		sensors

T15. Except for the buzzer embedded in motor and main board, robots are not allowed to equip with any other electrical sound equipment. Except for indicator lights built into main controllers and sensors that comply with technical specifications, light sources used in conjunction with sensors, and laser targeting devices that comply with technical specifications, robots may use RGB LED lights up to 5V (inclusive) for decoration or status display, provided they do not interfere with the operations of other teams.

T16. Teams are allowed to self-construct or procure mechanical parts. It is suggested to use complete commercial product components with low integration, such as

>>> 38 <<<-

hinges, sprockets, roller chains and pulleys, etc. It is not allowed to use highly integrated complete commercial products, including but not limited to multi-DOF manipulators or mechanical hand.

5.2 Specification for Team Flag

T17. The specification for team flag is as below:

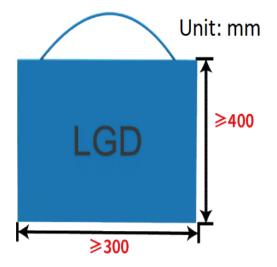


Fig. The Size of Flag

- The flag consists of flag surface and its suspension components.
- The flag surface must made of flexible materials, can be fabric, paper and other flexible materials.
- The flag suspension components include the flagpole and the suspension parts. Magnetic materials are prohibited for the suspension components. Hard materials are allowed for the flagpole part. the dimension of which should not be more than 400mm (L) * 10mm (W) * 10mm (H);
- The size of surface of the flag is no less than 400 mm (length) x 300mm (width).
 The flag surface needs to be a rectangular completed flag, and no cutting or special-shaped cutting is allowed;
- At most one flag for per team.
- The committee encourages teams to draw personalized patterns or words on the

39



flag, which calls for positive content reflecting competition theme and spirit, without showing words or pictures related to MakeX Robotics Competition Committee.

6.Competition Rules

6.1 Penalty

Violation

E01. The referee issues a violation to the team, and immediately deducted 20 points. In the meantime, the competition will not pause.

Suspension

E02. The referee issues a suspension to ask the robot to stop its action. The Referee is entitled to suspend robots according to the actual situation in the arena. The contestants shall ask the referee to suspend the robot while encountering robot malfunction or uncontrollably.

Yellow card

E03. If one constant's behavior seriously affects the competition fairness or violates the safety rules, the team or alliance will receive a yellow card with 60 points deductions.

Red Card

E04. If one contestant's behavior seriously affects the competition fairness or violates the safety rules, the alliance will receive 120 points deductions, and its robot will be suspended.

Qualification Round: When one contestant's or related person's action that extremely affect the fairness of the competition or violates the safety principle, the team will receive a red card with 120 points deductions. The violated robot will be suspended, but the match will continue as usual. If two teams of the alliance receive

the red card, the alliance will lose the match (if the score of the winner is lower than the losing team, the winner will receive extra 10 points higher than the final score of the losing team)

Elimination Round: If any team of the alliance receives a red card, the alliance will lose the competition. (If the score of the winner is lower than the losing team, the winner will receive extra 10 points higher than the final score of the losing team).

Disqualify For the Single Match

E05. During the match, the team violated the rules, the robot will be suspended immediately and resulting in invalidate of the score of the match, but did not affect the other matches.

Disqualify For the Entire Competition

E06. The robot will be suspended immediately and the team cannot participate in the competition and the following competition, all results will be disqualified. The team will lose the opportunity to continue to participate in the competition and the right to award.

6.2 Security Rules

The referee will issue a warning to the violator of the following security rules. If the behavior persists without correction, the robot will be disabled. If the violation causes damage to the arena or opponent's robot, a penalty of 120 points will be imposed and the robot will be disabled.

Dangerous Structure

R01. The measure of safety protection should be taken if robot's structure may cause damage to humans, such as sharp angles.

Destructing or Contaminating Arena

R02. During the competition, robots are not allowed to maliciously "climb" or "collide" the arena boundary and the central partition.

R03. If arena contamination caused by the robot, the robot will be regarded as in an

unsafe state. Robots are not allowed to use double-sided tape or glue to fix arena elements during competition.

Destructing Other Robots

R04. During the competition, robots must not intentionally collide, overturn, entangle, or damage other robots on the arena. Reasonable confrontation is not penalized under this rule, and the determination of whether an action is intentional is made by the on-site referee.

Robots Out of Boundary

R05. During the competition, any parts of robot are not allowed to go beyond the arena boundary. The robot that goes beyond the boundary must return to its own area within three seconds and the referee will give a countdown reminder.

Using Banned Materials

R06. The following hazardous materials or dangerous structures embedded in robot are forbidden, such as:

- Flammable gases, fire or smoke generating equipment, hydraulic oil or hydraulic parts, switches or contacts containing liquid mercury (mercury);
- (2) Hazardous Substances (e.g., Lead);
- (3) Materials that may cause arena contamination, such as sand and other objects that may be scattered during competition;
- (4) Materials that develop connections with other robots;
- (5) Materials with sharp edges that may cause injury.
- (6) Materials made from animal tissue (for health and legal consideration).
- (7) Materials containing liquids or gelatinous substances (except for glues and lubricants).
- (8) Parts that can conduct electrical current from robots to any other parts in arena.

>>> 42 **<<**<·



Other Unsafe Factors

R07. In addition to R06, referees are entitled to decide whether the robot is safe or not.

6.3 Contestants' Requirements

The referee will issue a warning to the violator of the following contestants' requirements. They will be required to make corrections. If a participant is unable or unwilling to comply with the rules, their qualification for the match will be revoked. In serious cases, the entire match results may be invalidated.

R08. One operator and one observer for each team. Each alliance includes two operators and two observers, one of them is selected to be the captain of the alliance.

R09. It is not allowed for a third person as a substitution of on-arena players during the match. Operators are responsible for controlling the robot in each match. The operator and the observer can freely switch their roles during the match.

R10. Contestants should tie up their long hair during competition preparation, robot debugging and on-field match. Toe-baring shoes are forbidden.

R11. Contestants should wear goggles during the competition.

Can't Arrival the Arena on Time

R12. Teams should arrive on time. Team that not show up in the competing area over 5 minutes, will be treated as give up this match voluntarily. If the whole competition schedule is delayed, please refer to the specific notice.

Contestants' Standing Position

R13. Contestants shall stand in certain range as shown in the following figure (the size of the operating area is subject to actual conditions):

>>> 43 **<<<**

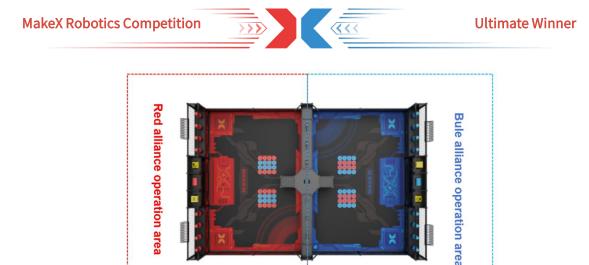


Fig. Standing Position of Operating Area

Rules of Elimination Round

R14. During the BO3 match in elimination round, after the end of each match, each alliance has 5 minutes for debugging their robot and cannot overtime.

Operating the Robot in Advance

R15. Robots are not allowed to operate until referee's announcement to start the competition.

6.4 Operation Rules

The referee will issue a warning to the violator of the following operational rules and require them to make corrections. If the violation occurs again, a penalty of 20 points will be deducted. Depending on the severity of the infraction, the referee may impose a deduction of 120 points.

Starting the match prematurely

R16. Robots must not be activated before the referee announces the start of the match.

Delayed end of the Competition

R17. After the end of automatic stage, manual stage and final stage, operator should stop controlling the robot or stop robot's operation program (except for the motion



caused by inertia).

Using Banned Electronic Device

R18. During the competition, it is not allowed for contestants to use electronic communication devices (mobile phone, transceiver, computer, wireless network devices and etc.) to get contact with the offsite people.

Using Bluetooth Controller in Automatic Stage

R19. Bluetooth controller should be connected with robot before the match. During the automatic stage, the blue-tooth controller should be place outside the arena; contestants are only allowed to pick up their blue-tooth controller after the automatic stage; after the manual stage, contestants must stop controlling their robot immediately.

Operating Suspended Robot

R20. The operator is not allowed to control the robot after the robot is suspended.

Robot's Left-Behind Components

R21. During the competition, the following situation is forbidden, such as detachment of robot and its component and left-behind mechanical devices (detachment refers to detachment of robot ontology and its components). This rule is exception to the shedding caused by collision of opponent's robot or direct contact with other robots.

Robot In-conformity during the competition

R22. The size of the robot should in the state that approved by both teams and the referees before the competition. Robots must comply with the size, weight and other parameters specifications during the match. Except for those situations that are caused by non-subjective factors, including being hit by opponents' arena element or other external forces, which leads to robots deforming or oversized.

Toss in Violation

R23. Robots are not allowed to toss any arena elements except for the discs from the

- >>> 45 <<<-



own camp to the to opponent's camp.

Violation of reversing flags:

R24. During the competition, no part of the robot may directly contact a flag and reverse it (contact that does not result in flag reversal is excluded). If such an incident occurs, the referee will immediately pause the match and restore the flag to its original position.

Enter Opponent's Camp

R25. Before the final stage, the vertical projection of the robot's chassis shall not partially or completely enter the opponent's area in any form.

- The robot that enters the opponent's area must return to its own area within three seconds and the referee will give a countdown reminder. If the robot fails to return its own area within 3 second, the team will receive a yellow card.
- If a robot partially enters the opponent's camp during the automatic stage, it must return to its own camp within 3 seconds after the start of the manual stage. Failure to do so will be considered a violation and result in a yellow card. If the robot fully enters the opponent's camp, it will be directly issued a yellow card and must return to its own area within 3 seconds after the start of the manual stage. Failure to comply will result in a robot suspension and removal from the arena.

R26. When the final stage begin, the vertical projection of the robot's chassis that is not allowed to enter the opponent's area shall not partially or completely enter the opponent's area in any form.

Restricting the movement of opponents' robot

R27. When the final stage begin, robots are not allowed to prevent robots that has get the benefit to enter their camp from entering their camps by restricting the movement of the centre fence, or by blocking them head-on, etc.

Entering opponents' area and offensive contact with opposing props

R28. When the final stage begin, robots that are allowed to enter the opponents area shall not directly or indirectly contact or using the discs to hit opponents' alphabet cubes and cones in the central resource island and the pins in the resource area and the hanging flag.

Restricting the Movement of Opponent's Robot

R29. Robots are not allowed to prevent the robot of opponents' alliance from moving in all directions or touching arena elements. As part of robot's ontology enters opponent's camp, which leads to the other side's alliance robot being stopped or restricted, the competition will be suspended based on actual situation, and robots of both alliances must be detached as soon as possible.

Contact in Violation

R30. Except for the Modification Stage, the contestants should not directly contact the arena elements such as the scoring props, the arena's frame and the robots etc. during the match, including but not limited to the cases where the operator leans on the fence and the contestants push the robot. In case the direct contacts occur outside the arena due to the normal movement of discs or other props, they are not bound by this rule.

Throughout the entire competition, robots may only change the state of flags by launching discs to strike them; they may not change the state of flags by directly or indirectly contact them.

Due to an advantage gained from unauthorized contact, the referee will pause the match and restore the flag to its original position.

Physical Interference

R30. In order to ensure an unblocked attacking router for opponent, team members should keep their body projection out of the arena during the competition. This rule is exception to the action of moving robots in and out of the arena during the modification stage.



Mentoring in Violation

R31. No person (including but not limited to the parents or mentors of the team) other than the team members shall enter the competition area by any means, and no instruction shall be given in or outside the competition area in any form.

Off-Arena Contact

R32. During the competition, contestants are not allowed to have any direct contact with off-arena person and audiences, including but not limited to the delivery of the parts and Bluetooth controller.

Malicious Complaints

R33. In a single match, it is prohibited for contestants to make malicious complaints against the opposing team.

6.5 Modification Rules

The Robot Not in the Starting Area Before Modification Stage

R33. At the end of the Manual Stage, the robot needs to be taken out from the Starting Area (partially or completed in the starting area) for modifications. In case the robot is not inside the Starting Area (Partially or Completely In), it will not be allowed to conduct any operations during the Modification Stage.

• The team who modifies the robot that is not partially or completed in the Starting Area will receive a red card and the robot will be suspended.

Modify Outside the Designated Area

R34. The team can only modify the robot after the vertical projection of the robot is completely out of the arena. Modification cannot be conducted when the robot is lifted just above the Arena.

>>> 48 <<<-

• Team who is against this rule will receive a Violation.

Changing the State of Arena Elements

R35. When taking the robot out of the arena, contestants are not allowed to contact those scoring props that has no contact with the robot or change the state of scoring props.

 The team will receive a violation. An invalid point will be given to those offenders who take the advantage as a result of changing the state of arena elements. Besides, the offender is required to reset the original state of the arena.

R36. When taking the robot out of the arena, the robot cannot carry with any scoring props except for the discs. The other scoring props shall be place into the arena nearby.

• The offence team will receive a violation.

The Robot Not Inside the Starting Area Before the End of Modification Stage

R37. The robot shall be placed in their own Starting Area before the end of the Modification Stage.

• The robot who is against this rule will be suspended.

The modified robot failed to match the check-in status.

R38. The robot after the Modification Stage should conform with the modification state at the time of inspection, including but not limited to the Maximum Modification Size. (The height of Robot is not limited.)

• The offence robot will be suspended.

7. Appeal and Arbitration

7.1 Results Confirmation

Results Confirmation

When a single match ends, captains of both teams need to confirm the results with the referees and then sign the scoring sheet. Both teams shall not have any objection to the results of this single match after their signatures.



Dispute Settlement

If the team has any objections to the results and referee's explanation, they can refuse to sign the score sheet. Instead, they need to write clearly about the situation on the remarks part of the result form.

7.2 Appeal Procedure and Valid Appeal Period

Appeal Procedure

Appeals should be lodged within the "valid appeal period" by the prescribed procedure and follow the civil participation spirit. The captain of the team needs to fill in the Appeal Form, then cooperates with the Arbitration Commission to investigate actual situation. Both sides will be required to arrive at the designated place if the Arbitration Commission requires. During the investigation, the captain of the appeal team must be present, and only captains or contestants of both teams can be present. The Arbitration Commission has the right to communicate with the team alone, avoiding the mentor, the parents of the contestants, their relatives, or friends. The appellant should express facts clearly and objectively, not being over-emotionally.

Valid Appeal Period

Normally, the appeal should be lodged within 30 minutes after the end of the competition. Please check the Program Brochure for a specific effective appeal period before the competition. The appellant and the respondent must be present at the designated place on time.

Appeal Response

Normally, the Arbitration Commission responds to the appeal after the end of the competition on the same day or before the start of the competition on the next day.

>>> 50 **<<<**



7.3 Invalid Appeal

Overdue Appeal

Appeals that are not lodged within the "valid appeal period" will be considered invalid and inadmissible. If the appellant fails to be present on time or leaves without any reason during the investigation, the appeal will be considered invalid. If the respondent fails to be present on time, the Arbitration Commission will directly determine the arbitration result and render it as a final result.

Appellants out of Stipulation

The appellants must be the participating contestant and the appeal of another person is inadmissible. The Arbitration Committee will caution the offending team if parents, mentors, or other persons out of the stipulation participate in the arbitration process without the permission of the Arbitration Committee.

 Team or alliance will be disqualified entire competition for multiple invalid warnings.

Vague Appeal's Requests

If the Arbitration Commission is unable to understand the appeal or conduct the normal investigation due to emotion factor of the appealing party, the offending party will receive a verbal warning.

 Team or alliance will be disqualified entire competition for multiple invalid warnings.

Uncivil Appeal

Neither side shall make uncivil behavior nor offensive action and remarks.

 Team or alliance will be disqualified entire competition for multiple invalid warnings.

>>> 51 <<<-



7.4 Arbitration Procedure

Arbitration Procedure

The Arbitration Commission consists of the chief referee, the arbitration consultant, and the competition technical director. The Arbitration Commission is responsible for accepting the appeals and conducting arbitration investigations, to ensure the smooth progress of the competition and the fairness and justice of the competition results. The playback videos and photographs of any competition may be inaccurate due to the shooting angle, which is only used as reference but not arbitration evidence.

Arbitration Results

The arbitration results can be divided into "maintaining the original result of the match" or "re-match", and the two teams shall not appeal again. If the arbitration result is a "re-match", the two teams shall have a re-match according to the time and arena stipulated in the Appeal Form. If either team fails to reach the arena within 5 minutes after the beginning of the match, the team shall be deemed to quit the match.

Additional Remarks

The Arbitration Commission determines the final arbitration result, and neither side shall dispute the result of the appeal anymore.

8.Statement

MakeX Robotics Competition Committee reserves the final interpretation of 2024 MakeX Challenge Ultimate Winner Rules Guide.

8.1 Rules Explanation

In order to ensure a fair competition and high-quality competition experience,

>>> 52 <<< -</p>

MakeX Robotics Competition Committee has the right to update and complement this Rules Guide regularly, issue and implement the latest version before the competition.

During the competition, all matters not stated in the Rules Guide shall be decided by the referee team.

This Rules Guide is the basis for refereeing, and the referee team has the right of adjudication during the competition.

8.2 Disclaimer

All contestants in MakeX Robotics Competition shall fully understand that safety is the most important issue for the sustainable development of the MakeX Robotics Competition. To protect the rights and interests of all contestants and organizers, according to relevant laws and regulations, all contestants registered for the 2024 MakeX Robotics Competition, shall acknowledge and abide by the following safety provisions:

- (1) Contestants shall take adequate safety precautions when constructing the robots, and all parts used for constructing the robots shall be purchased from legal manufacturers.
- (2) Contestants shall ensure that the structural design of the robots takes into account the convenience of the inspection and actively cooperate with the host of the competition.
- (3) When modifying and using the parts with potential safety hazards for the robots, it must conform to the national laws, regulations, and quality & safety standards. Those operations shall be manufactured and operated by persons with relevant professional qualifications.
- (4) During the competition, the teams shall ensure that all the actions such as construction, testing, and preparation will not do harm to their team and other teams, referees, staff, audiences, equipment, and arenas.

(5) In the process of construction and competition, if any action that may violate the national laws, regulations, or standards occur, all consequences will be borne by the contestants themselves.

The competition kits and parts sold and provided by the supporter, MakeX Robotics Competition Committee, shall be used by the instructions. MakeX Robotics Competition Committee will not be responsible for any injury or loss of property caused by improper use.

The official language for MakeX is Chinese. English or other language translations are prepared to facilitate the team's preparation process. All documents translated to English are for reference only.

8.3 Copyright Declaration

MakeX Robotics Competition Committee reserves the copyright of this Rules Guide. Without the written consent or authorization from MakeX Robotics Competition Committee, any entity or individual may not reproduce, including but not limited to any network media, electronic media or written media.

Appendix 1. Awards and Annual Points

In 2024 season, according to the scale of the competition and the number of teams, the competition will be classified into Points Race/Regional Competition, National Competition, International/Intercontinental Competition, and World Championship. In MakeX Challenge Ultimate Winner competition, teams can obtain the points based on the number of wins, ties and losses in the match. Each team can voluntarily sign up for all kinds of Points Race all year round to accumulate the annual points. The accumulation of annual points is based on the Team Number.

>>>

In single points race, teams can obtain annual points based on the winning points in qualification round and elimination round.

Competition Type	Rounds	Win	Tie	Loss
Points Race/Regional	Qualification	5	2	1
Competition	Elimination (Best of 3)	10	/	2
	Qualification	10	4	2
National Competition	Elimination (Best of 3)	20	/	4
International/	Qualification	15	6	3
Intercontinental Competition	Elimination (Best of 3)	30	/	6

Teams that have won the champion, runner-up, second runner-up and other awards can obtain additional annual points. For the details of award list, please refer to **2024 MakeX Awards Guide.**

Category	Awards	Regional /Points Race	National	International/ Intercontinental
	Champion	15	30	45
	Runner-up	10	20	30
Special	Second runner-up	5	10	15
Award	Innovative Design Award	-	5	10
	Engineering Notebook Award	-	5	10
Comprehensive Award	Outstanding Mentor Award	-	-	-
Awaru	Promotion Ambassador	-	5	10

- >>> 55 <<<<-



			MARCO// CONSTRUCTION
Award			
Technology Sharing Award	-	5	10
MakeX Spirit Award	-	-	10

>>>

For example, team X20000 obtains the champion in one Points Race, and all the results show as below.

Qualification Round	Qualification Round	Qualification Round	Qualification Round	Annual Points from
1	2	3	4	Qualification
Win (5)	Loss (1)	Tie (2)	Win (5)	Round=13
Top Eight Battle	Semi-final	Final		Annual Points from
		Win (10)		Elimination
Win (10)	Win (10)			Round=30

The total annual points that team X20000 obtains = 13+30+15 = 58.

Appendix 2. Engineering Notebook Guideline

*Instruction:

1. The value of engineering notebook: It helps the team establish files and record the whole learning process. Therefore, it is necessary to record engineering notebook during the entire preparation for the competition.

2. Engineering notebook submission: Teams can use online documents or handwriting. No matter which way to use, each team must submit a paper version onsite.

Paper engineering notebook: As the Challenge & Premier programs require the



assessment process, one copy of the paper version shall be submitted by each team to the judges onsite. If there is no assessment process (Starter & Explorer), each team will need to submit one copy of the paper version to the staff at the inspection area. Teams that cannot submit the original engineering notebook should prepare their own copies.

3. An engineering notebook will be required for the evaluation of all technical awards. Please refer to the Competition Guide for the evaluation criteria.

Basic Requirements for Cover

The team's name, team number, and competition program must appear on the cover of the engineering notebook.

Basic Requirements for Contents

1. Clear content

Creating content brings convenience for the judges to review and quickly find the corresponding section.

2. Process records (Required)

Every improvement of the robots should be recorded from prototype design, construction, to the debugging. Keep pictures of all manuscripts, design drawings, calculation processes, circuit diagrams, etc., and insert them into the engineering notebook in the form of pictures.

1) Schedule of robot building progress

- 2) Design inspiration/sketch
- 3) Technical principle (it can be disassembled into different parts)
- 4) Production step by step (with clear pictures)
- 5) Problems encountered and solutions

Examples of problems:

What technical failures did you encounter? Why did you fail? How did you solve the problems finally?

What efforts have you made for the robots? What improvements have been achieved?

Does your project progress schedule go as planned? What accidents or delays have occurred? How to fix it?

Have there been any disputes among the team members and how to settle them in the end?

3. Projects summary

- 1) The structure and function of the project (with pictures and text enclosed)
- 2) The technical innovations of the project
- 3) Competition strategies for scoring and defense
- 4. Team introduction
- 1) A brief biography of each team member and their role on the team
- 2) Culture displaying (logo, team flag, slogan, posters, T-shirt, etc.)
- 3) Excellent achievements sharing (Stories)
- 5. Feelings and other things you want to share (optional)
- 1) Achievement in the competition (Technical)
- 2) Growth in the competition (Spiritual)
- 3) Suggestions for competition

Appendix 3 Robot Self-Check Form

MakeX Challenge Ultimate Winner

Robot Self-Check Form

Please follow the requirements of the self-checklist and check the box if your robot meets the requirements. And submit the signed self-checklist during the inspection day. Thanks for your cooperation.

Team Number:	am Number: Team Name:		
Actual attended Team Member: _			
		58	< <<



Mentor Name: _____

1. B	1. Basic Information			
	-	Nodule Bit Code: f numbers and alphabet, eg: 004C)		
(Rob	ot size should r	mm, Wide mm, Height not exceed: length 500mm, width 500mm, height nd fill in the maximum extension size)		
Rob	ot Weight:	kg (Should not exceed 10kg)		
(Flag	g surface is no le	n mm, Wide mm ss than 400mm(length)* 300mm(wide). The flag su the flagpole is allowed to use hard materials)	face is made of	
2. E	quipment			
Qua	ntity of DC moto	or&Encoder motor (37DC Motor&180 Smart Encod	er Motor) ≤ 13]Yes	
Serv	os (MS-12A) ≤ 6		Yes	
Brus	h-less Motor (282	$3/2824$ Brush-less Motor) ≤ 2	Yes	
	ntity of Bluetooth eless control: Blue	controller: 1Yestooth version: BT4.0Yes		
Nam	e and parameters	of battery: (3S Li-Po Battery, Output Voltage: 11.1V		
Disc	harge Rate: 25-30	c, Battery capacity: 4200mAh) 🛛 Yes		
Qua	ntity of battery is	one.		
3. C	others			
SN	ltems	Specific Requirements	Meet Requirement	
1	Dangerous	The robot's structure that may do harm to people	Meet	
	Structure	is required to ensure safety protection during robot handling and transporting.	Requirement	
2	Competition Area Destruction	Competition area destruction is prohibited in the process of robot loading, unloading and transporting.	☐Meet Requirement	
3	High-power	High-power equipment is not available during	Meet	



	Equipment	assembling and operating the robot.	Requirement	
4	Unsafe Energy Storage Equipment	Please keep safe while using energy storage devices (spring).		
5	Banned Material	Robots are not allowed to use the flammable gases, pyrotechnic equipment, hydraulic components, mercury-containing components, exposed hazardous materials, unsafe counterweights, designs that may cause entanglement and competition delays, sharp edges and angles, materials containing liquids or gelatinous substances, and any part that the electric current on the robot may be conducted to the competition area.	☐Meet Requirement	
6	Personal Safety	Contestants shall wear goggles; long hairs shall be tied up; contestants are prohibited from wearing toe-baring shoes to enter the competition area.	□Yes	
7	Luminous/Aco ustic Sensor	Excluding the built-in buzzer of the motor and main control unit, the robot is not allowed to use any electronic sound-producing devices. Aside from the indicator lights of the main control and sensors that comply with technical specifications, light sources used in conjunction with sensors, and laser aiming devices that meet technical specifications, the robot may use RGB LED lights with a voltage of 5V or below (including 5V) for decoration or status display, provided they do not interfere with the operation of other teams. If a laser aiming device modified from a teaching laser pointer requires separate power, only the built-in paired battery (such as AA batteries) may be used, and it must not supply energy to the robot's power system. For uncommon laser aiming devices, please provide the corresponding model and parameters for verification.	☐Yes	

_____>>> 60 **<**<< _____



			00000022222
8	Self-Customize d Parts and Accessories	Self-customized parts can be used: plates, profiled materials, 3D printing pieces, metals, wood, plastics, rubber, magnets; Usage requirements for auxiliary materials: It is allowed to use the ropes, cables, wires, springs, rubber bands, leather hoses, surgical tubing, punched sheets, injection molded products; It can use commercial product components with low integration instead of higher integration.	□Yes
9	Wrap the Sharp Structure	The exposed sharp edges of the robots have to be wrapped with sponge strips.	□Yes
10	Detachment/S hedding	Detachment of the robot and its component is forbidden during the competition.	□Yes
11	Interference	It is prohibited to interfere with the electronics and sensors of other robots.	□Yes
12	Team Number	Team number's printing font should be Microsoft YaHei, black bold, 130 font sizes, and the background should be in light color.	□Yes
13	Engineering Notebook Submission	Submitting project notebook containing robot control source code before the competition.	□Yes
14	Contaminating Competition Area	The lubricant and other materials used by robots shall not contaminate the arena or other robots.	□Yes

>>>

Our team has checked our own robot according to the self-check form and has filled in the actual data on this form and submitted it to MakeX Robotics Committee. We promise that we will participate in the competition in the above state and will report any changes in time. During the competition, if the robot does not comply with the requirement or our team uses any in-compliance robot, the competition result will be disqualified and all responsibilities will be taken by the team without objection.

->>> 61 <<<-

Team Leader Signature: Date:

Appendix 4 MakeX Challenge Score Sheet

MAKE C ROBOTICS COMPETITION

2024 MakeX Challenge Ultimate Winner--Scoring Sheet

Competition Info: Qualification Round \Box / Elimination Round \Box (Arena) No. (Session)

Team Registration		Match Points				
Red Alliance	Red Alliand Score & Quar		Blue Alliance ty Score & Quantity			
Team 1 (No.) :	20points/each	Discs 20	pts/each	20points/each	Red Alliance	
realiti (NO.) .	10points/each	Pins 20p	ots/each	10points/each		
Team 2 (No.) :	20points/each	Reseve Flag	20pts/each	20points/each		
	50points/each	Cube or cone	e 50pts/each	50points/each		
Blue Alliance		Additional 100pts				
Team 1 (No.) :	<i>Own 30pts Opponent</i> <i>50pts</i>	Hanging Flag		<i>Own 30pts</i> <i>Opponent 50pts</i>	Blue Alliance	
Team 2 (No.) :		Penalty				
		Total Points				
Captain of Red Alliance:	Captain of Red Alliance: Referee of Red Alliance			Remark		
(Please confirm the scoring results and sign here)	(Please confirm the scoring results and sign here)					
Referee of Red Alliance:	Referee of Blue Alliance:			(If there's any disagreement about the results, please write down the situation clearly and sign here.)		
(Please confirm the scoring results and sign here) (Please confirm the scoring sign here)		oring results and				

Appendix 5 Instructions for Li-Po Battery

To ensure the safety of Li-Po battery, each team should designate a person to supervise the usage of battery, and to inform the teammates about the safety instructions for Li-Po battery. The following issues should be noted while using Li-Po battery:

- Please use the Li-Po battery while ensuring that you carefully read and understand the safety instructions.
- Safely charging and discharging.
- It is required to use the specified charger for Li-Po battery provided by the manufacturer, as well as read the instructions for charger carefully. In case of emergencies to be dealt with, please ensure that someone is nearby during charging. Please do not overcharge or over-discharge. It will be deemed overcharge if the voltage of a single battery cell is over 4.2v, and less than 3.0v is over-discharge. Overcharge may cause the explosion of the Li-Po battery, while over-discharge can easily damage the battery and shorten the service life of it.
- Please check the battery's voltage and electricity quantity carefully before charging or using.
- Please charge the battery at 0-45 °C.
- Safe storage
- The battery cell cannot be overheated any time. When the temperature of the battery cell is as high as 60°C, there will be potential safety hazards, even burning.
- In the process of charging, the battery is not required to be closely or placed directly on flammable materials (paper, plastic, etc.). If conditions permit, it is best to charge it in a fire-proof safe box.

• > > > 63 <<<< -

- Please do not put batteries near liquids, open fire or heaters. Place batteries out of reach by kids.
- Please do not detach and restructure the batteries arbitrarily or change its wiring, do not assemble the batteries privately. The following behaviors are deemed as dangerous: detach and restructure the old battery cells, or restructure one of the detached battery cells with another restructured one (It can easily cause short-circuit combustion without the particular assembly instrument).
- If occurs collision during the competition, please take out the battery. Please carefully check the state of battery and connector. (Note: Batteries may be overheated with high temperature.)
- Do not spill electrolyte on eyes or skin. In case it spills inadvertently, please wash it with clean water immediately. In case it is serious, please seek medical care immediately.
- No short circuit is allowed (positive and negative poles are connected).
- Do not directly contact the leaked battery.
- For batteries that are not used for a long time, please ensure a charge-discharge activation within 3 months to maintain the stability.
- During the storage and transportation of Li-Po batteries, please place them in the special fire-proof safety bags or safety boxes.

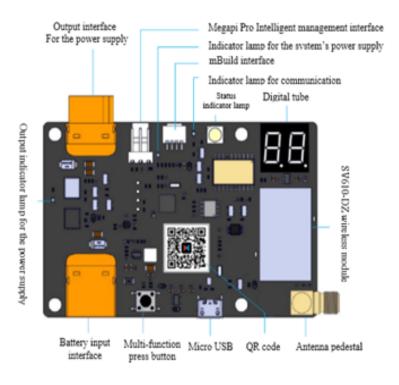
>>> 64 **<<**

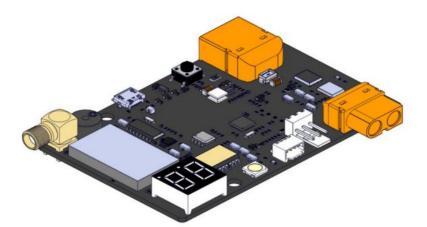
Appendix 6 Power Management Module

Introduction of Power Management Module

The power management module is used in coordination with the main board (NovaPi), which is a necessary electronic device to participate in the competitions of 2024 Season Ultimate Winner and Ultimate Warrior.

Module Size: 85mm(length) x 56mm(width) x 11.5mm(height);







Working Voltage: 6V - 12V;

On-board LED Lamp

LED Lamp includes an indicator lamp for power output, an indicator lamp for system power and an indicator lamp for communication

- Indicator Lamp for Power Output: The red indicator lamp is always on when having power output, and goes off when the power is disconnected.
- Indicator Lamp for System Power: The red indicator lamp for system power is always on when the module is working.
- Indicator Lamp for Communication: The blue indicator for lamp communication flashes when the module updates its firmware.

Indicator Lamp for Status (RGB Lamp)

Indicator lamp for status mainly includes four statuses: power off, red, green and blue.

- Power Off: The Bluetooth module is detected after the power management module is powered on. The RGB lamp is powered off when the Bluetooth module cannot be detected.
- Red: After a normal power-on, click the button and the RGB lamp flashes red once;
- **Green:** In manual stage;
- Blue: In automatic stage.

Digital Tube

The two-digit digital tube is mainly used to display the current channel and an abnormal state of the wireless communication module.

- In the normal state, the channel number of the current wireless communication module is displayed by the two-digit digital tube. The channel number of the wireless communication module is 1~40, so that the number displayed by the digital tube is 1~40. If the current channel is 16 channels, the two-digit digital tube displays the number "16".
- The power management module will detect the wireless communication module when it is powered on. If the wireless communication module

- >>> 66 **<<<-**





cannot be detected, the 2-digit digital tube will display the letter "Er", meaning error.

 When the battery is low powered, the two-digit digital tube displays the symbol "-" and the current channel number alternately.

Buzzer

The buzzer will send the sounds of reminding and warning.

- The buzzer will shortly buzz when the module is normally powered on and be detected, together with the wireless communication module is online;
- When the power management module is reset, the buzzer will sound for 2 seconds;
- When the wireless communication module cannot be detected after power-on, the buzzer rings three times continuously.

Operation of Power Management Module

Multi-function Button

Multifunctional button has four modes: reset, click, double-click and long-press.

- Reset: Firstly, press the multi-function button and meanwhile insert the Li-Po battery into the power management module. The power management module restores the default configuration parameters. The buzzer sounds for 2 seconds and the digital tube displays the number "20";
- **Click:** Click the multi-function button once, the power management module reports the Bluetooth module UID once, and the RGB lamp flashes red once.
- Double Click: Double click the multi-function button once, the power management module will delay 3 seconds and switch between the automatic program and manual program (It can be observed whether the state switch is successful through the RGB indicator, the RGB blue lamp is always on during automatic stage, the RGB green lamp is always on during manual stage, and the RGB lamp flashes during the delayed switching). Double click is only valid when the Bluetooth module is the defaulted to "20" channel (It is only valid when the digital tube displays the number



"20");

• Long Press: Long press the multi-function button (2-3 sec.) to switch the output state of the power supply. That is if the current power is disconnected, the power will connect after long pressing and its indicator lamp becomes red. If the power connects, the power will disconnect after long pressing and its indicator lamp powers off.

Starting Signal Identification Code of Automatic Program

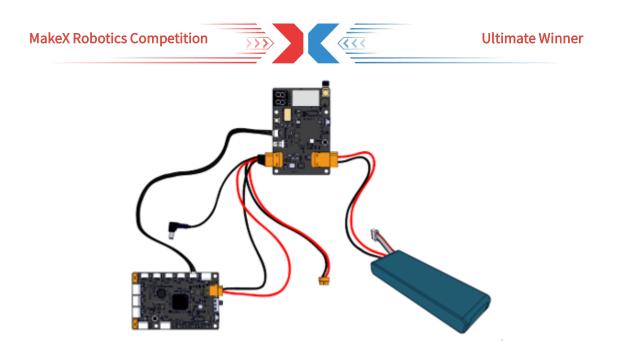
In automatic stage, the competition system sends relevant instructions to the power management module of the robot, so as to shield the controller signal and start the automatic program of the robot. In order to start the automatic program on the mainboard normally, it is necessary to insert a fixed code into the program to identify the instructions to start the automatic program sent by the competition system.

NovaPi Main Program	define Manual procedure			
forever	★ encoder motor M1 ▼ rotates at power 50 %			
if Competition is in Automatic Stage? then Automatic program else	define Automatic program			
Manual procedure	✓ encoder motor M2 ▼ rotates at power 50 %			

(Please put the program in manual stage and automatic stage into the corresponding positions.)

Installation Manual

- The power management module is a necessary electronic component for the competition. Please make sure that it is securely fixed, and cables are tightly connected. For protection, it is suggested to use an acrylic box of power management module;
- The data cables leading to the mainboard must be connected firmly as follows:



- Adjust the position of the antenna to prevent it from interfering with the movement of other motion devices, and try to avoid the antenna exposed to metal materials;
- The power management module must be fixed on the surface of the robot and be accessible to scan (power management module ID);
- The following operations are not allowed at any stage after the start of the competition, especially during the modification stage:
 - The replacement of Li-Po battery or re-unplugging and re-plugging of the Li-Po battery.
 - b. Press the reset button of the power management module (any operation of the power management module is prohibited).
- When the competition is finished, the robot needs to be re-powered by itself, and the power supply can be restored by unplugging and plugging the Li-Po battery;
- The power management module corresponds to the teams' information in the competition system one by one. Please do not replace that module without authorization. If it needs to be replaced, please contact the staff. Any problems caused by the unauthorized replacement of the power module shall be borne by the team.

Appendix 7 Supplementary Explanation of Competition Procedure

Engineering Notebook Submission

MakeX Robotics Competition Committee encourages teams to record engineering notes, and excellent notes will be an important basis for team's award evaluation. The submission of paper engineering notebook and award setting based on pre-match notice and program brochure. Generally speaking, the submission of paper engineering notes is a necessary in medium and large-scale events, which will serve as an important basis for the award evaluation. Please refer to **Appendix 2 Engineering Notebook Guideline**.

Pits Area Decoration

Each team has its own space in the pits area, where teams can decorate their space to make their teams known to people, and participate in the award evaluation. Teams can rest and debug robots in the pits area, and please keep the area clean and tidy. The suggestions are as follows:

- 1. Display Content (provided by teams)
 - (1) Team Flag
 - (2) HD Images (3-4 copies)
 - (3) Team Introduction (no more than 200 words)
 - (4) Peripheral Display (if any)
- 2. Display Form

Team Poster/Roll Up Banner + Team Flag + Team Peripheral (if any) + Team Members/Teachers' Onsite Suggestion

Practice Round

Teams who have finished their robot inspection can participate in practice round. The schedule will be announced at the entrance in form of notices, and teams are required to queue in line before entrance. Not all competitions have a practice round,



which can be informed based on actual situation.

Team Assessment

MakeX encourages contestants to master theoretical knowledge of robots as well as develop their creativity and skills of making robots by participating in the competition. By the method of Q&A and onsite problem-solving, the assessment with 10 minutes will be conducted to examine students' knowledge of robots. In this procedure, all team members must participate together except their mentors. Each team should attend the assessment on time, with 1 copy of the engineering notebook and the robot.

The assessment, with its aim to examine students' knowledge of robot, will be conducted in three aspects, including basic robotics theory, machinery and programming as well as innovation. The judges will ask questions or require an onsite operation demonstration. In a regular points race, teams can obtain different score (5, 3, 2, 0) based on their onsite performance grade (S, A, B, C). The assessment result will be announced on the MakeX official website after the qualification round. Teams obtaining zero point in the assessment procedure will not be able to enter the elimination round. The assessment score will be adjusted accordingly for different grade of point races.

>>> 71 **<<**<

Appendix 8 Competition Resources

Competition resources include but are not limited to official resources provided by the committee, such as Competition Guide, Equipment Instructions, Rules Videos, etc.

The contestants are obliged to keep abreast of the update of competition resources before the competition, and any problems caused by the contestants' failure to keep abreast of the updates shall be borne by the contestants themselves. All official competition resources will be updated in MakeX Website.

MakeX Robotics Competition Committee will revise and improve the Rules Guide with the progress of the competition and the new version will be announced in MakeX Website. The contestants and mentors can download the latest version in MakeX Website.

MakeX Website Download https://www.makex.cc/en/information/download.

MakeX Official Website: https://www.makex.cc/en.

Any Feedback & Question Please Sent to:

makex_overseas@makeblock.com

MAKE)

Edited By Makex Robotics Competition Committee

Official Website: www.makex.cc/en

Emaill: makex_overseasa@makeblock.com



f Facebook : Makex